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### **1. S3.05: Power Electronics and Management, and Energy Storage**

Release Date: 07-18-2011Open Date: 07-18-2011Due Date: 09-08-2011Close Date: 09-08-2011

Future NASA science objectives will include missions such as Earth Orbiting, Venus, Europa, Titan/Enceladus Flagship, Lunar Quest and Space Weather missions. Under this subtopic, proposals are solicited to develop energy storage and power electronics to enable or enhance the capabilities of future science missions.

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### **2. S3.06: Guidance, Navigation and Control**

Release Date: 07-18-2011Open Date: 07-18-2011Due Date: 09-08-2011Close Date: 09-08-2011

Advances in the following areas of guidance, navigation and control are sought. Navigation systems (including multiple sensors and algorithms/estimators, possibly based on existing component technologies) that work collectively on multiple vehicles to enable inertial alignment of the formation of vehicles (i.e., pointing of the line-of-sight defined by fixed points on the vehicles) on the level of milli-arcseconds relative to the background star field.

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### **3. S3.07: Terrestrial and Planetary Balloons**

Release Date: 07-18-2011Open Date: 07-18-2011Due Date: 09-08-2011Close Date: 09-08-2011

NASA's Scientific Balloons provide practical and cost effective platforms for conducting discovery science, development and testing for future space instruments, as well as training opportunities for future scientists and engineers. Balloons can reach altitudes above 36 kilometers, with suspended masses up to 3600 kilograms, and can stay afloat for several weeks. Currently, the Balloon Program is on the verge of introducing an advanced balloon system that will enable 100-day missions at mid latitudes and thus resemble the performance of a small spacecraft at a fraction of the cost.

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### **4. S3.08: Unmanned Aircraft and Sounding Rocket Technologies**

Release Date: 07-18-2011Open Date: 07-18-2011Due Date: 09-08-2011Close Date: 09-08-2011

All proposals should show an understanding of one or more relevant science needs, and present a feasible plan to fully develop a technology and infuse it into a NASA program. Unmanned Aircraft Systems

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### **5. S4: Low-Cost Small Spacecraft and Technologies**

Release Date: 07-18-2011Open Date: 07-18-2011Due Date: 09-08-2011Close Date:

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**Low-Cost Small Spacecraft and Technologies** This subtopic is targeted at the development of technologies and systems that can enable the realization of small spacecraft science missions. While small spacecraft have the benefit of reduced launch costs by virtue of their lower mass, they may be currently limited in performance and their capacity to provide on-orbit resources to payload and instrument systems.

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## **[6. S4.01: Unique Mission Architectures Using Small Spacecraft](#)**

Release Date: 07-18-2011 Open Date: 07-18-2011 Due Date: 09-08-2011 Close Date: 09-08-2011

Advancements in space technologies can now enable discussions on how small spacecraft might be used to assemble or form large space structures, which are significantly more capable than the individual spacecraft unit, while exploiting the advantages of small spacecraft such as low unit and launch costs.

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## **[7. S5: Robotic Exploration Technologies](#)**

Release Date: 07-18-2011 Open Date: 07-18-2011 Due Date: 09-08-2011 Close Date: 09-08-2011

NASA is pursuing technologies to enable robotic exploration of the Solar System including its planets, their moons, and small bodies. NASA has a development program that includes technologies for the atmospheric entry, descent, and landing, mobility systems, extreme environments technology, sample acquisition and preparation for in situ experiments, and in situ planetary science instruments.

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## **[8. S5.01: Planetary Entry, Descent and Landing Technology](#)**

Release Date: 07-18-2011 Open Date: 07-18-2011 Due Date: 09-08-2011 Close Date: 09-08-2011

NASA seeks innovative sensor technologies to enhance success for entry, descent and landing (EDL) operations on missions to Mars. This call is not for sensor processing algorithms. Sensing technologies are desired that determine the entry point of the spacecraft in the Mars atmosphere; provide inputs to systems that control spacecraft trajectory, speed, and orientation to the surface; locate the spacecraft relative to the Martian surface; evaluate potential hazards at the landing site; and determine when the spacecraft has touched down.

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## **[9. S5.02: Sample Collection, Processing, and Handling](#)**

Release Date: 07-18-2011 Open Date: 07-18-2011 Due Date: 09-08-2011 Close Date:

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Robust systems for sample acquisition, handling and processing are critical to the next generation of robotic explorers for investigation of planetary bodies ([http://books.nap.edu/openbook.php?record\\_id=10432&page=R1](http://books.nap.edu/openbook.php?record_id=10432&page=R1)). Limited spacecraft resources (power, volume, mass, computational capabilities, and telemetry bandwidth) demand innovative, integrated sampling systems that can survive and operate in challenging environments (e.g., extremes in temperature, pressure, gravity, vibration and thermal cycling).

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### **10. [S5.03: Surface and Subsurface Robotic Exploration](#)**

Release Date: 07-18-2011 Open Date: 07-18-2011 Due Date: 09-08-2011 Close Date: 09-08-2011

Technologies are needed to enable access, mobility, and sample acquisition at surface and subsurface sampling sites of scientific interest on Mars, Venus, small planetary bodies, and the moons of Earth, Mars, Jovian and Saturnian systems.

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